

The Microkernel Overhead

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HelenOS

Why am I Here?

- HelenOS developer since 2005
- Computer science researcher
 - Distributed and component systems
 - Formal verification of OS correctness
- Monolithic and microkernel OSes have both their **pros** and **cons**
 - The microkernel overhead is a particular source of many misconceptions

For the sake of brevity, some of the following slides might be oversimplified.

When making important decisions, always consult the original references, rely on your own observations and draw your own conclusions.

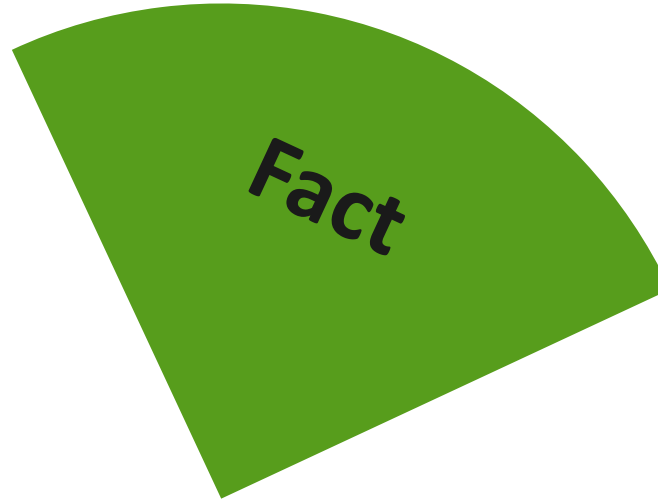
The Overhead?



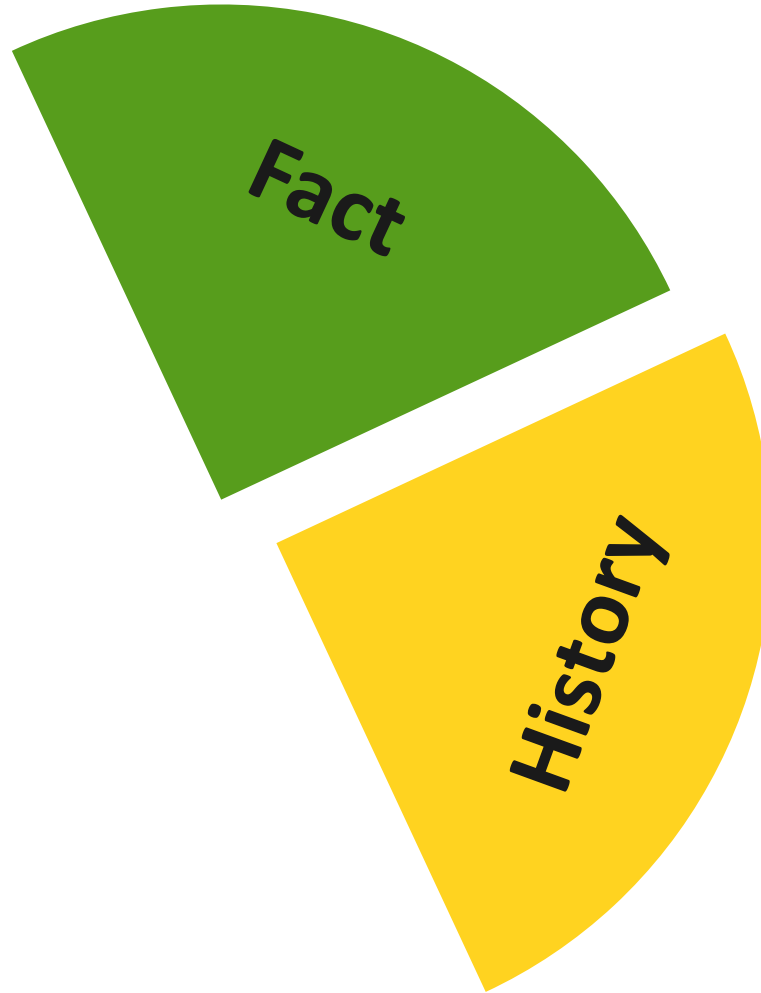
HelenOS



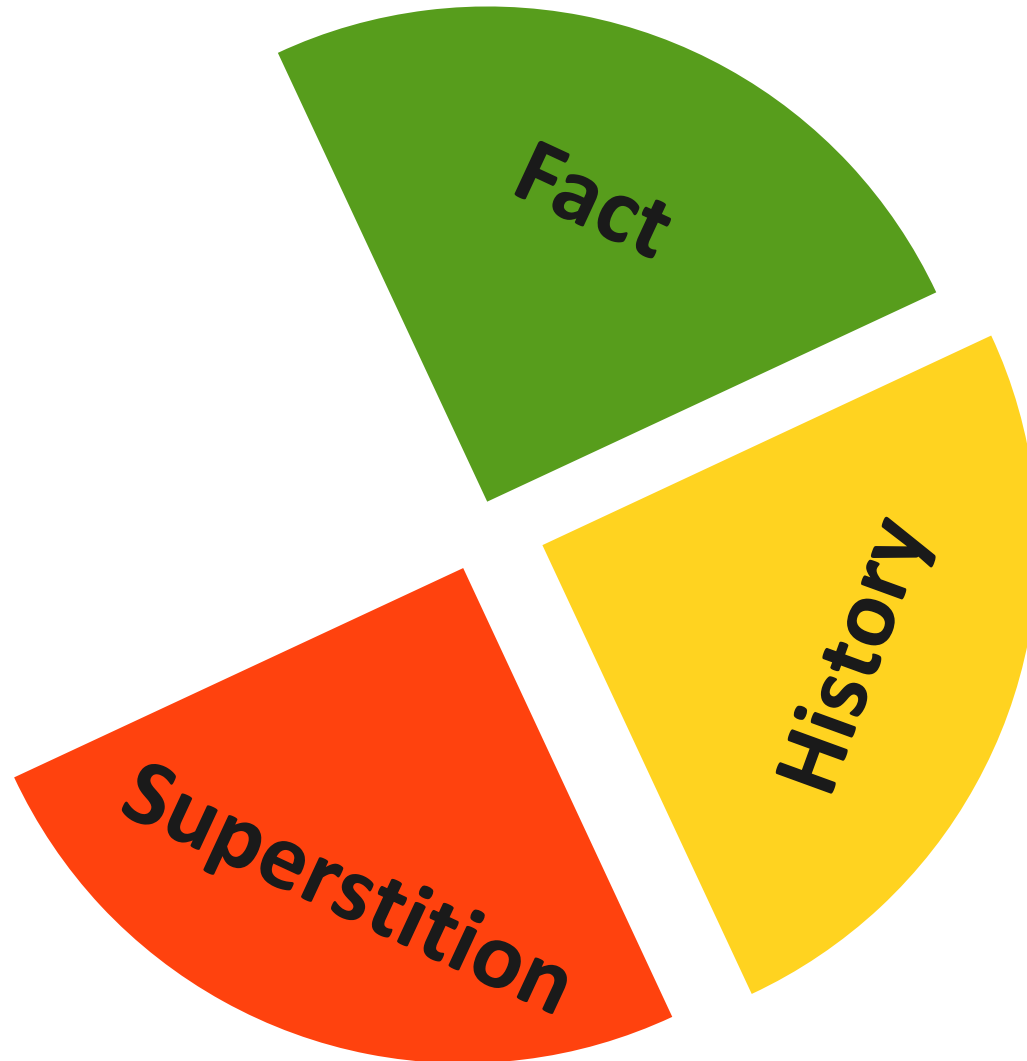
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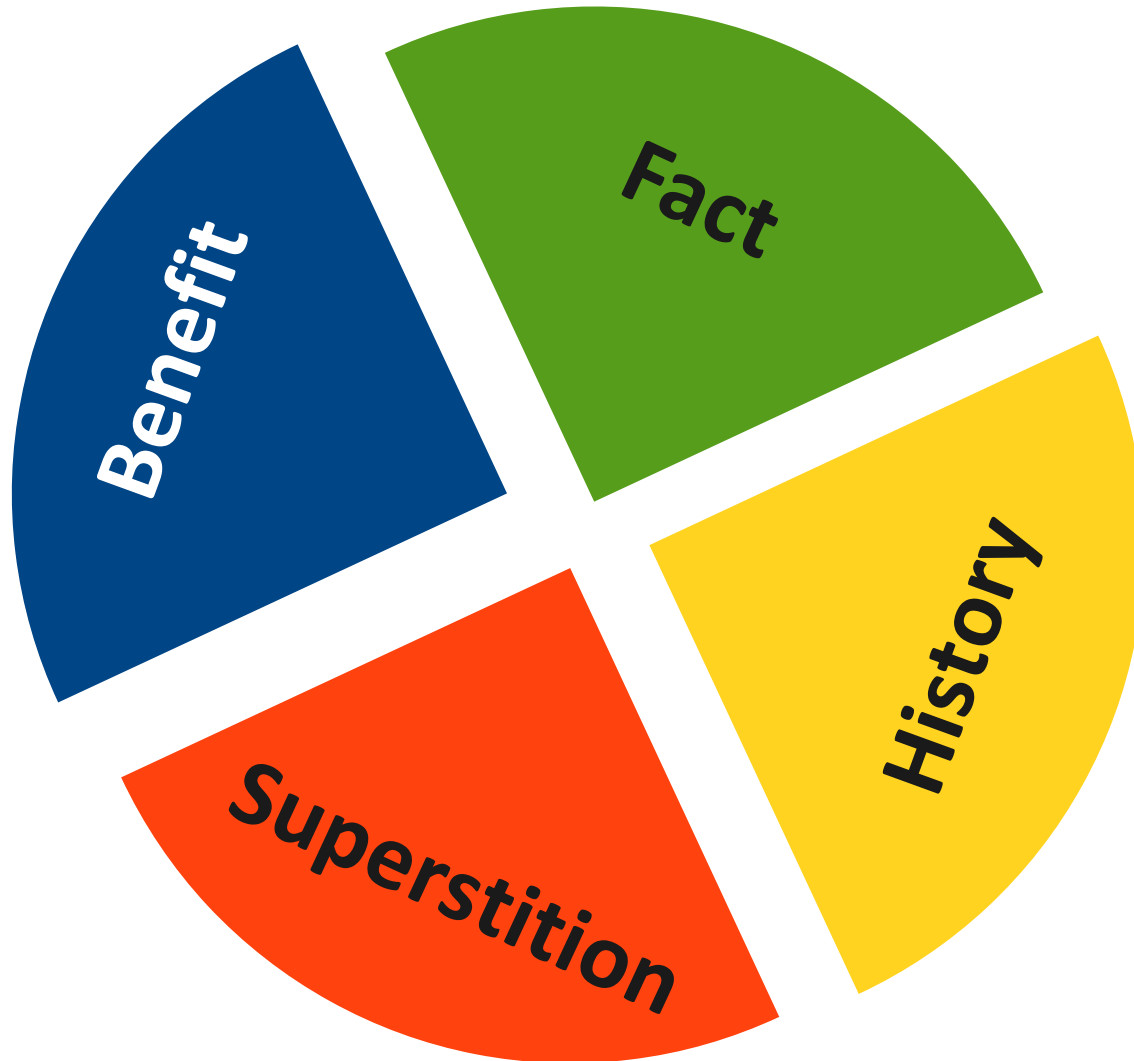
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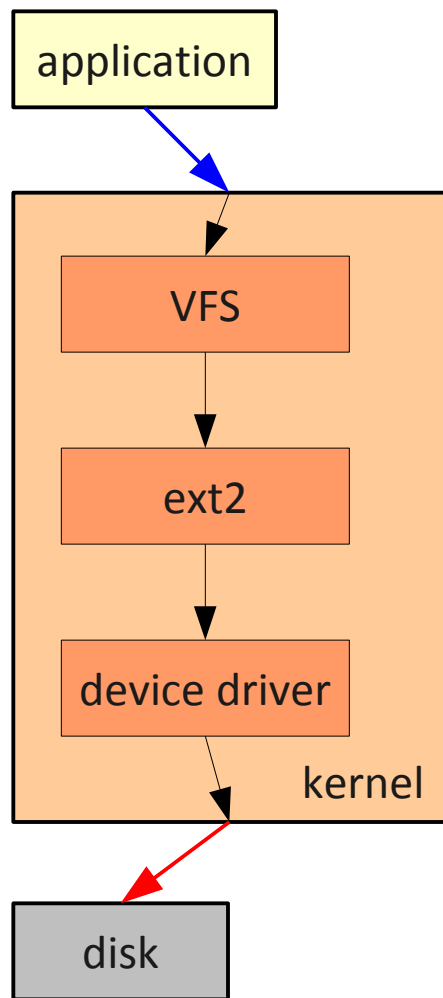
The Overhead?



Microkernel Overhead as a Fact



Monolithic kernel



user space

kernel

hardware

syscall

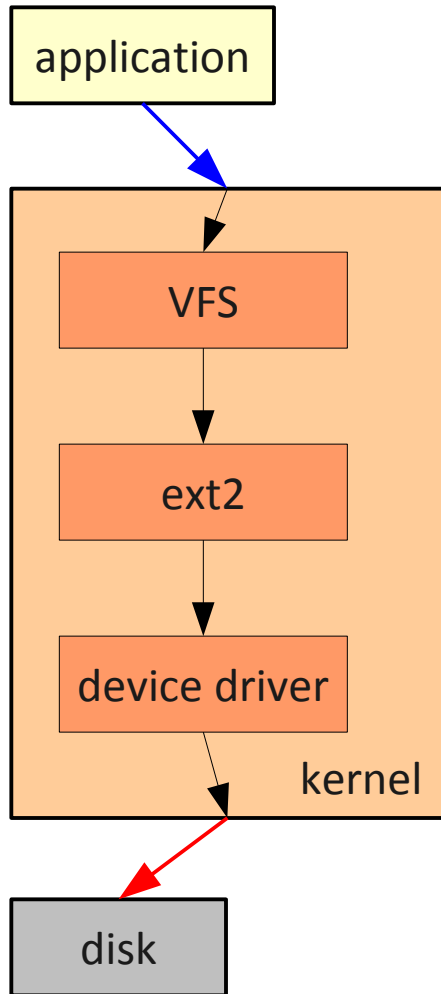
function call

I/O

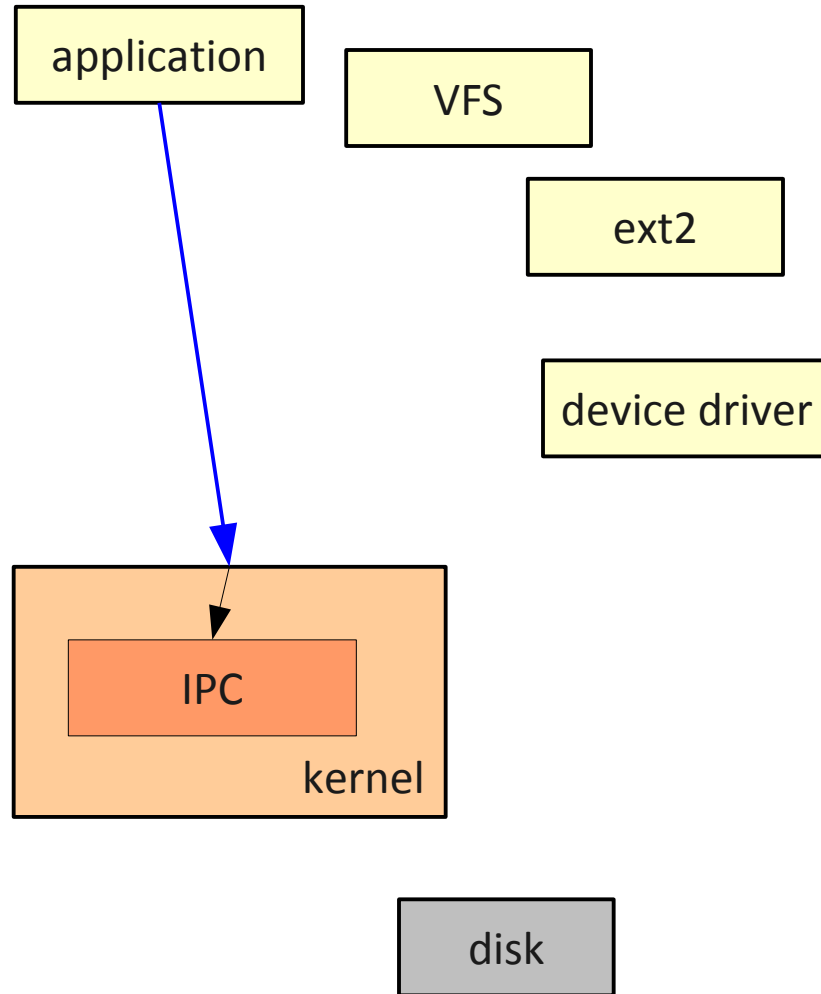
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Monolithic kernel



Microkernel

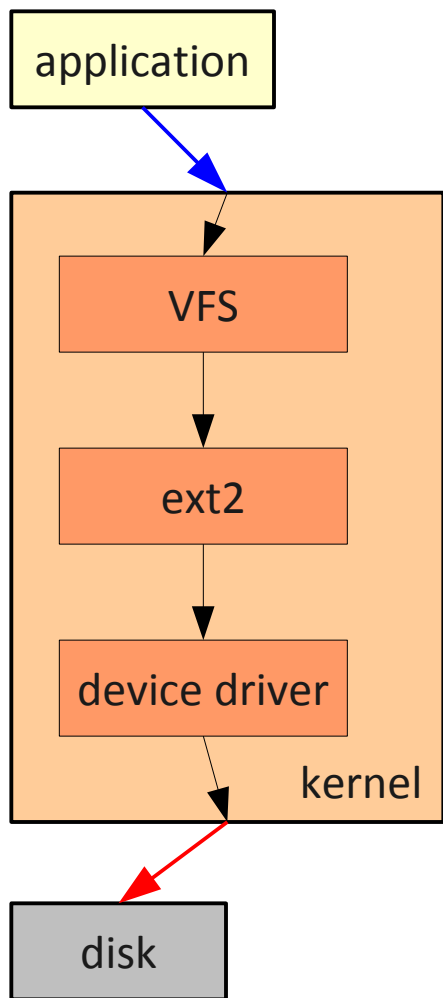


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- syscall
- function call
- I/O

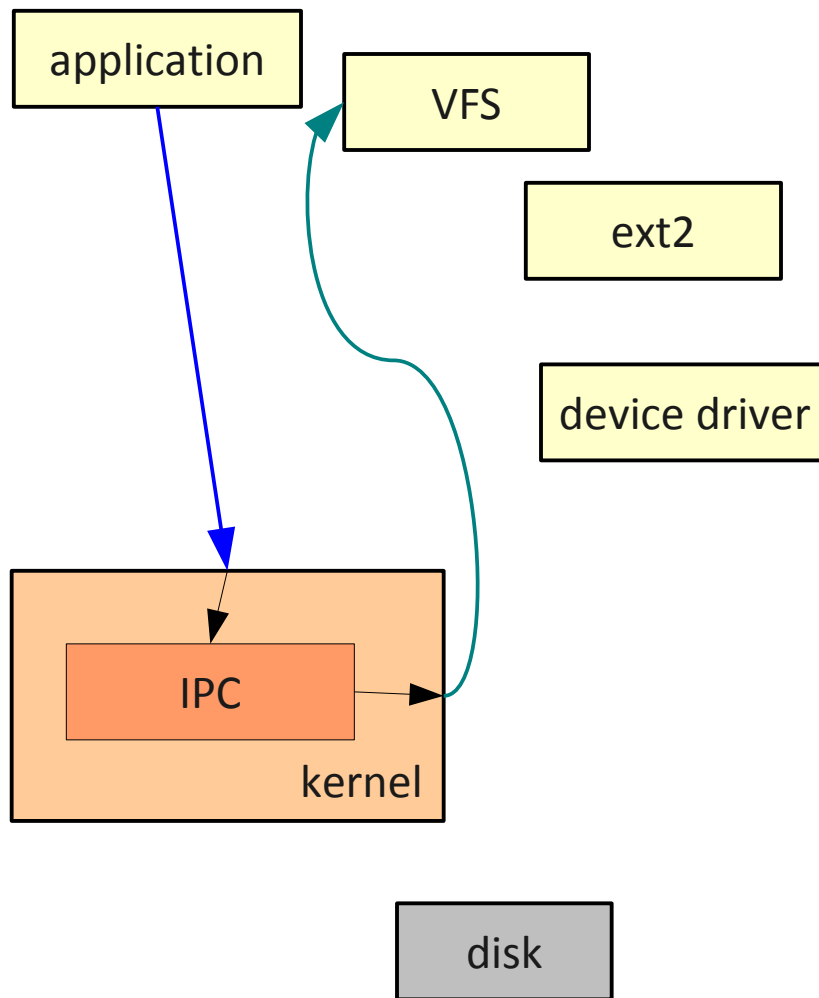
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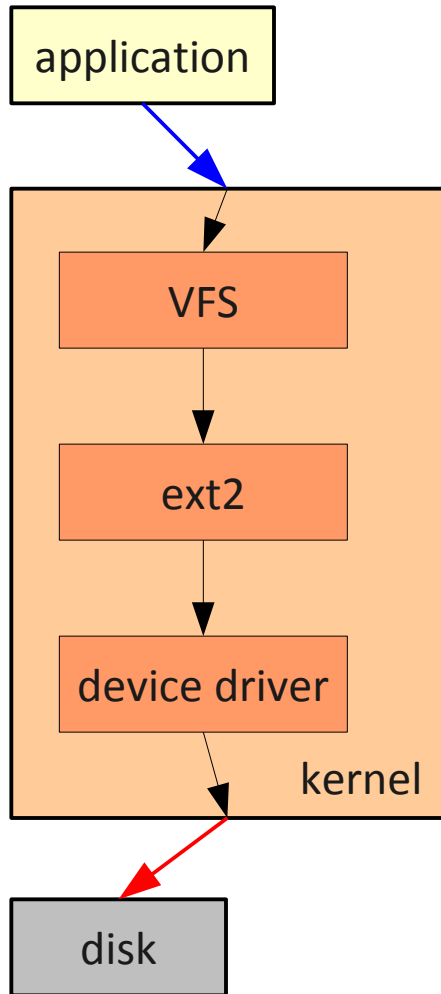


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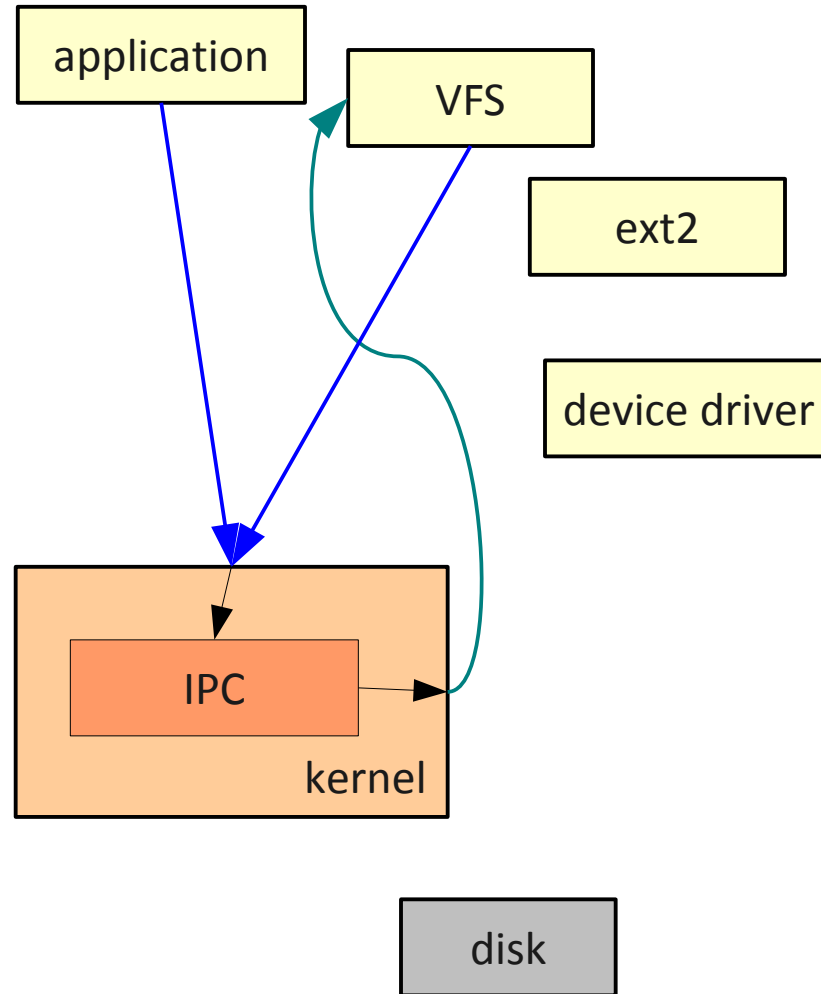
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Monolithic kernel



Microkernel

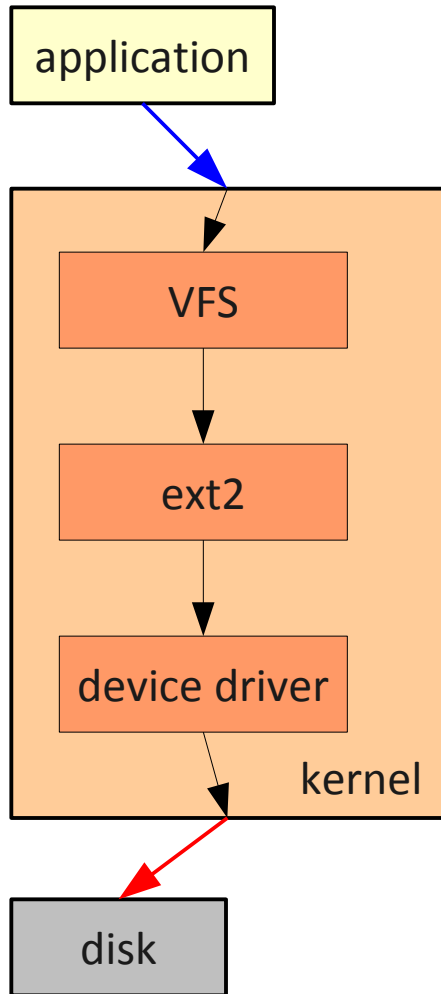


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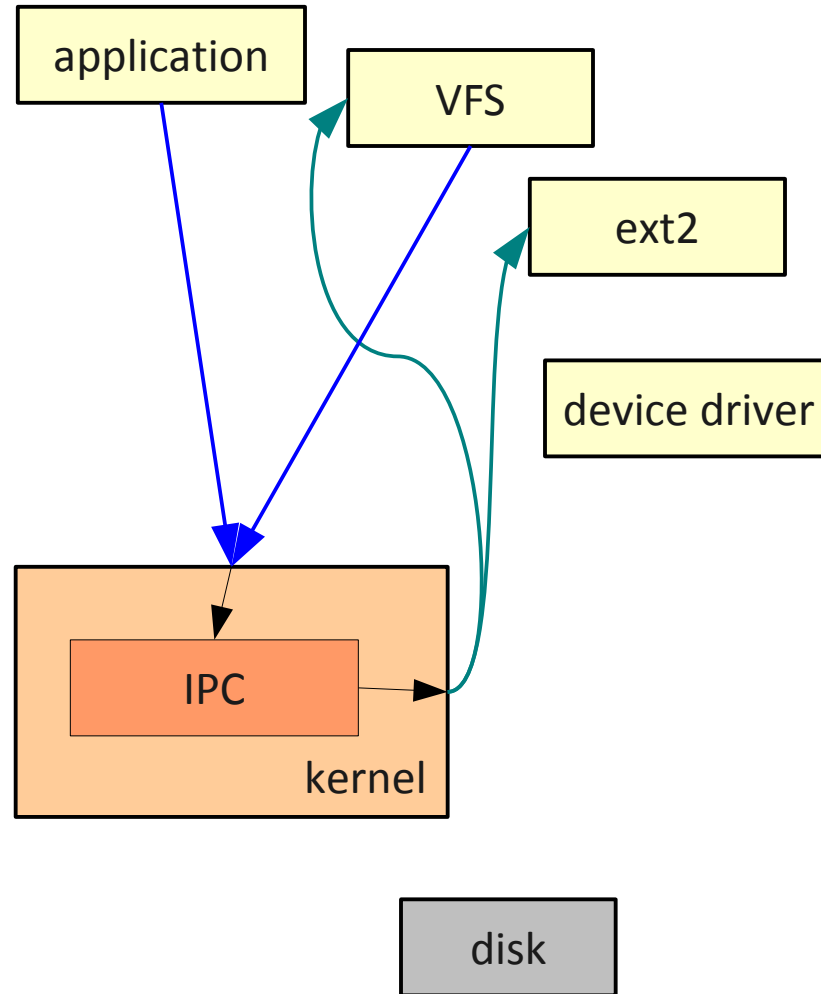
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Monolithic kernel



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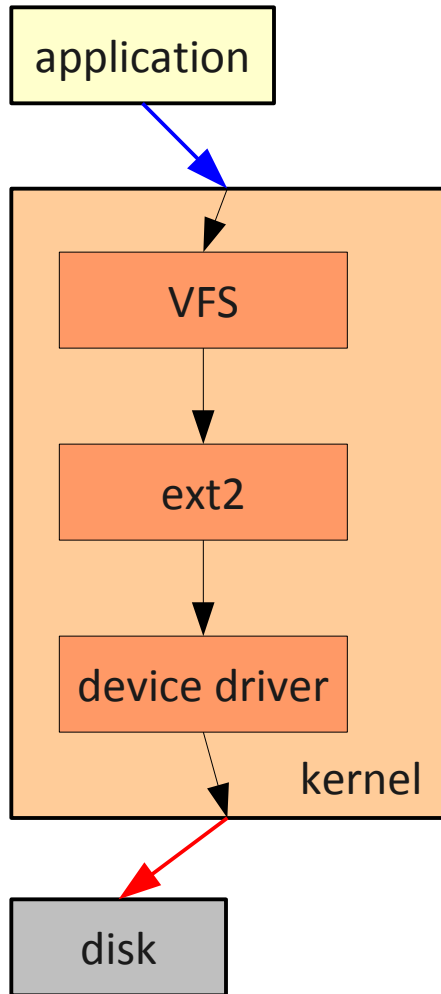


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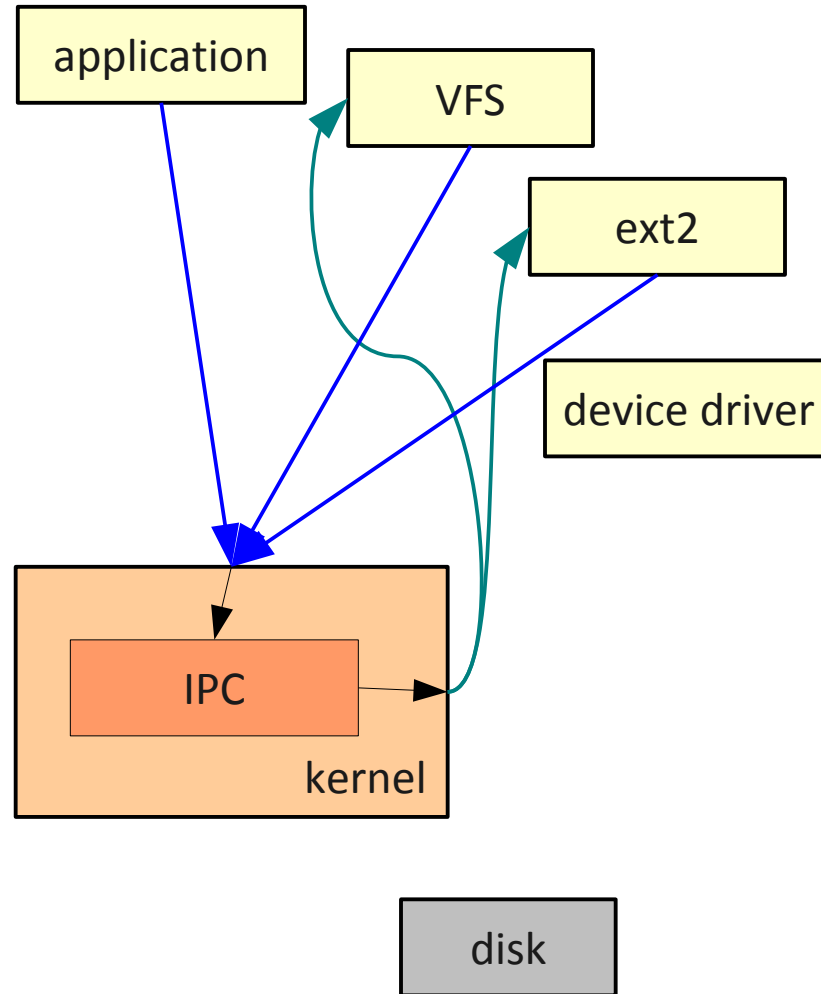
Microkernel Overhead as a Fact



Monolithic kernel



Microkernel

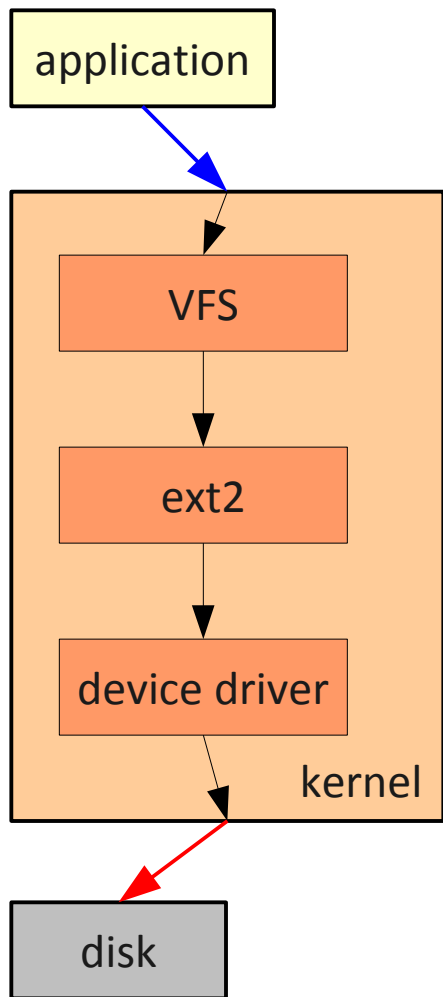


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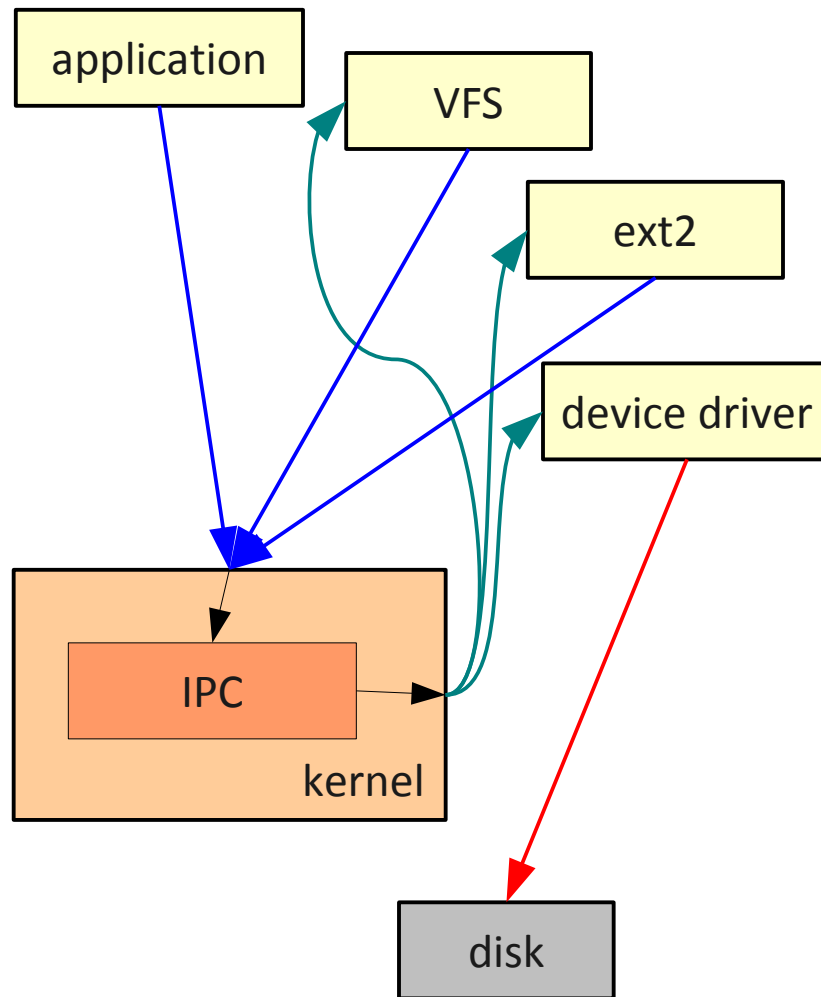
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Monolithic kernel



Microkernel



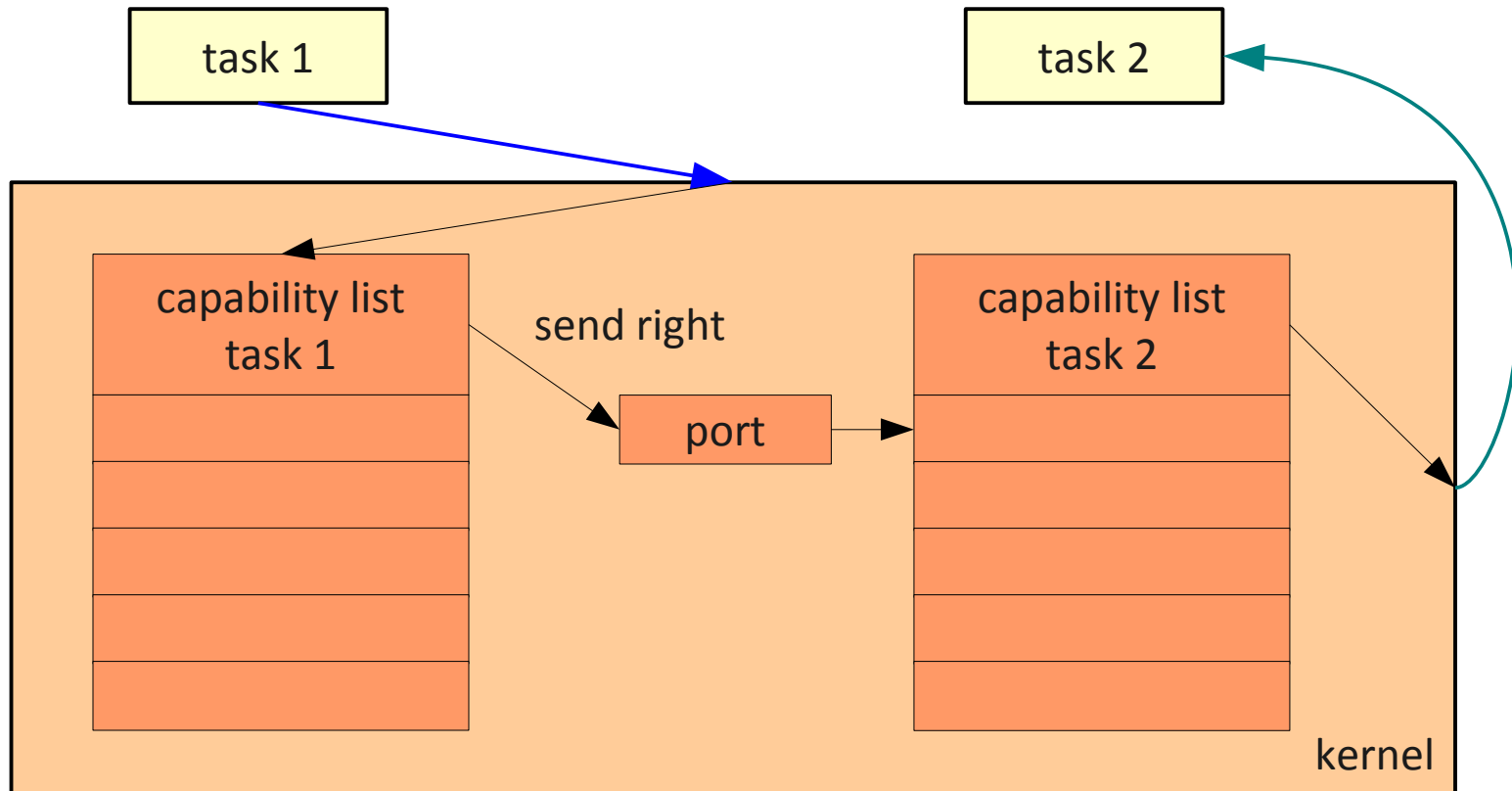
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- Natural reasons for the microkernel overhead
 - **More communication barriers**
 - Function call → Upcall + Syscall
 - Synchronous execution → Context switch
 - **Heavier operations**
 - Jump → Mode switch
 - Argument passing → Argument queuing
 - → Scheduler execution
- What is the actual extent of the overhead?

- Benchmarks of Mach 3.0 (1997)
 - Single-server Mach vs. UNIX slowdown: **1.5×**
 - 73 % of the slowdown due to IPC overhead
 - 80 % of the IPC overhead due to access rights and message validity checking
 - Communication barriers are unavoidable
 - It is the very cornerstone of microkernel design
 - Not accountable for more than a 3× higher overhead (not 3× higher slowdown)
 - The problem are the heavy operations

Microkernel Overhead in History (2)

- Mach asynchronous IPC



- Mach asynchronous IPC
 - Complex access rights evaluation in the kernel
 - Complicated queuing in the kernel
 - Simple data structures (linked lists)
 - Excessive cache footprint
 - Sequential programming paradigm
 - IPC used mostly in synchronous manner

- Benchmarks of L4 (1997)
 - Single-server L4 vs. UNIX slowdown: **1.03×**
 - Single IPC call overhead comparable to single UNIX syscall overhead
 - 20× faster than on Mach
 - The slowdown caused only by the communication barriers
 - Even the overhead of a multiserver variant expected to be rather reasonable

- L4 synchronous IPC
 - Explicit client/server rendez-vous
 - No need for full context switch
 - Data passed directly in registers and in shared memory
 - No rescheduling, no queuing
 - Highly optimized implementation
 - Small working set
 - Better spatial locality, cache friendly
 - Leaving the access right policies to the user space servers

- Mach 3.0 is a (too) well-known failed example
 - First-generation archetypal microkernel
 - Establishing the terminology, etc.
 - Part of university curricula all over the world
 - Never practically used as a microkernel with user space drivers
 - XNU: Single-server microkernel with **kernel drivers**
 - Hurd: Multiserver microkernel with **kernel drivers**

- Opinion of the general public
 - Tanenbaum-Torvalds debate (1992)
 - Performance of microkernels mentioned several times
 - Hybrid design of Windows NT
 - Kernel space device drivers
 - Microkernel modularity, but a single address space
 - *“Microkernels are just research toys”*
 - *“Real-life performance demands monolithic kernels”*

- Let's consider a theoretical $1.5\times$ slowdown

- A 50 % faster CPU required to compensate

- In 1996

- Intel Pentium @ 133 MHz \$300

- Intel Pentium @ 200 MHz \$599

$2\times$

- In 2012

- Intel Xeon X5650 @ 2.67 GHz \$1004

- Intel Xeon X5690 @ 3.47 GHz \$1660

$1.66\times$

- The microkernel trade-off

- Run-time performance

- We have to pay more to compensate for the overhead

VS.

- Run-time reliability

- We have to pay less because of improved reliability
 - Fault isolation, restarting of faulty services
 - Formal verification

- When can an overhead be of any benefit?
 - Technically: **Never**
 - **Paradigm shift**
 - Plain function calls optimized and unbeatable for sequential code performance
 - What if sequential code execution cannot utilize the hardware effectively?
 - Multicore (many-core) architectures

- Parallel algorithms
 - Manual decomposition into work queues
 - Fork-join
 - Parallel programming abstractions
 - Actors, agents, dataflow concurrency, continuations
 - Future objects, promises
 - **Implementation level**
 - Similar to asynchronous IPC and multiserver design
 - Sequential overhead, but improved throughout

- HelenOS asynchronous IPC
 - Elimination of unnecessary context switches
 - Cooperative scheduling in user space
 - Elimination of data copying
 - Shared memory between communicating tasks
 - Kernel queuing with reasonable performance
 - Smart concurrent data structures (hash tables, B+ trees)
 - No complex access rights, small code footprint
 - Asynchronous nature suitable for parallel processing
 - Non-blocking operations
 - Concepts of future objects and promises

- Benefits of monolithic systems
 - Easier global prediction of resource usage patterns
 - I/O caches and buffers
 - Across various subsystems (block layer, filesystem layer, directory layer, etc.)
 - Read-ahead heuristics
 - Simpler reaction to resource pressure conditions
 - Mild vs. aggressive cache flushing, graceful degradation
 - Easier scheduler interaction
 - Priority boosting for interactive tasks, etc.

- Resources in microkernel multiserer systems
 - Implicitly shared resources (and their state) scattered among isolated servers
 - No central point for caching, future usage prediction (read-ahead), resource pressure evaluation (out-of-memory)
 - Possible solutions
 - Polymorphic caching server
 - Distributed shared resource management

- The microkernel overhead is a fact
 - Inherent property of the microkernel design
 - A price paid for the improved reliability & design
- The way the microkernel is implemented dramatically affects the extent of the overhead
 - From two-fold or worse slowdown to only several percents

- Clever asynchronous IPC can provide adequate throughput on multicore systems
 - Non-blocking, non-sequential programming
 - Parallel processing of requests
- The resulting trade-off
 - Cost of hardware vs. Cost of reliability
- Still challenges to be solved
 - Transparent shared resources management



Q&A

- **Jochen Liedtke**: *Improving IPC by Kernel Design*
- **Jochen Liedtke**: *On μ -Kernel Construction*
- **Hermann Härtig, Michael Hohmuth, Jochen Liedtke, Sebastian Schönberg, Jean Wolter**: *The Performance of μ -Kernel-Based Systems*
- **Jan Stoess**: *Towards Effective User-Controlled Scheduling for Microkernel-Based Systems*
- **Sebastian Ottlik**: *Reducing Overhead in Microkernel Based Multiserver Operating Systems through Register Banks*